# Dynamische und regionale Ozeanographie WS 2014/15 

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## Lecture \# 9

## Recapitulation

Elementarstromsystem
Ekman transport
Ekman pumping
Sverdrup transport
Sverdrup meets Ekman

Wind driven circulation
Western boundary currents
oral examination Tuesday July 7., 2015

- 13:00 Tabea Kilchling
- 13:30 Isabell Hochfeld
- 14:00 Lucas Schmidt
- 14:30 Annika Buck
- 15:00 Elena Hirschhoff
- 15:30 Heninng Dorff
- 16:00 Jerome Sauer
- 16:30 Carolin Meier ?
- 17:00 Sophie Specht ?
- 17:30 Anna Wünsche ?

- Schematic of the near-surface circulation (after Schmitz 1996). Subtropical gyres are red, subpolar and polar gyres blue equatorial gyres magenta, Antarctic Circumpolar Current is blue green lines represent exchange between basins and gyres


## Recapitulation

## Elementarstromsystem

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Sverdrup meets Ekman

Wind driven circulation
Western boundary currents

- momentum equation in vector form for $R o \ll 1$

$$
f \boldsymbol{k} \times \boldsymbol{u}=-\frac{1}{\rho_{0}} \nabla_{h} p+\frac{1}{\rho_{0}} \frac{\partial \boldsymbol{\tau}}{\partial z} \text { with } \boldsymbol{k} \times \boldsymbol{u}=(-v, u, \emptyset)
$$

- $\boldsymbol{\tau}=\left(\tau^{x}, \tau^{y}\right)$ is a stress vector with $\tau(z=0)=\boldsymbol{\tau}^{a}$ where $\tau^{a}$ is the surface wind stress in $\mathrm{N} / \mathrm{m}^{2}$ acting on the ocean
- momentum equation in vector form for $R o \ll 1$

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f \boldsymbol{k} \times \boldsymbol{u}=-\frac{1}{\rho_{0}} \nabla_{h} p+\frac{1}{\rho_{0}} \frac{\partial \boldsymbol{\tau}}{\partial z} \text { with } \boldsymbol{k} \times \boldsymbol{u}=(-v, u, \emptyset)
$$

- $\boldsymbol{\tau}=\left(\tau^{x}, \tau^{y}\right)$ is a stress vector with $\boldsymbol{\tau}(z=0)=\boldsymbol{\tau}^{a}$ where $\boldsymbol{\tau}^{a}$ is the surface wind stress in $\mathrm{N} / \mathrm{m}^{2}$ acting on the ocean
- split the flow into geostrophic and frictional (Ekman) components, $\boldsymbol{u}=\boldsymbol{u}_{G}+\boldsymbol{u}_{E}\left(\right.$ and $\left.w=w_{G}+w_{E}\right)$, governed by

$$
f \boldsymbol{k} \times \boldsymbol{u}_{G}=-\frac{1}{\rho_{0}} \nabla_{h} p \quad \text { and } \quad f \boldsymbol{k} \times \boldsymbol{u}_{E}=\frac{1}{\rho_{0}} \frac{\partial \boldsymbol{\tau}}{\partial z}
$$

and the same for continuity equation

$$
\boldsymbol{\nabla} \cdot \boldsymbol{u}_{G}+\frac{\partial w_{G}}{\partial z}=0 \quad \text { and } \quad \boldsymbol{\nabla} \cdot \boldsymbol{u}_{E}+\frac{\partial w_{E}}{\partial z}=0
$$

- sum $\boldsymbol{u}_{G}+\boldsymbol{u}_{E}$ satisfies full momentum and continuity equation
- Elementarstromsystem (for $\rho=$ const)
- $\boldsymbol{u}=\boldsymbol{u}_{G}+\boldsymbol{u}_{E}\left(\right.$ and $\left.w=w_{G}+w_{E}\right)$
surface and bottom Ekman layers superimposed on geostrophic flow



## Recapitulation

## Elementarstromsystem

Ekman transport
Ekman pumping Sverdrup transport Sverdrup meets Ekman

Wind driven circulation
Western boundary currents

- vertically integrated velocity

$$
\boldsymbol{U}=\int_{-h}^{0} \boldsymbol{u} d z=\int_{-h}^{0}\left(\boldsymbol{u}_{G}+\boldsymbol{u}_{E}\right) d z=\boldsymbol{U}_{G}+\boldsymbol{U}_{E}
$$

- vertically integrated velocity

$$
\boldsymbol{U}=\int_{-h}^{0} \boldsymbol{u} d z=\int_{-h}^{0}\left(\boldsymbol{u}_{G}+\boldsymbol{u}_{E}\right) d z=\boldsymbol{U}_{G}+\boldsymbol{U}_{E}
$$

- with the (total) transport vector $\boldsymbol{U}$, dimension $\mathrm{m}^{2} \mathrm{~s}^{-1}$
- vertically integrated velocity

$$
\boldsymbol{U}=\int_{-h}^{0} \boldsymbol{u} d z=\int_{-h}^{0}\left(\boldsymbol{u}_{G}+\boldsymbol{u}_{E}\right) d z=\boldsymbol{U}_{G}+\boldsymbol{U}_{E}
$$

- with the (total) transport vector $\boldsymbol{U}$, dimension $\mathrm{m}^{2} \mathrm{~s}^{-1}$
- transport by the geostrophic velocity $\rightarrow$ geostrophic transport $\boldsymbol{U}_{G}$ transport by the Ekman velocity $\rightarrow$ Ekman transport $\boldsymbol{U}_{E}$

$$
f \boldsymbol{k} \times \boldsymbol{u}_{E}=\frac{1}{\rho_{0}} \frac{\partial \boldsymbol{\tau}}{\partial z}
$$

- vertically integrated velocity

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\boldsymbol{U}=\int_{-h}^{0} \boldsymbol{u} d z=\int_{-h}^{0}\left(\boldsymbol{u}_{G}+\boldsymbol{u}_{E}\right) d z=\boldsymbol{U}_{G}+\boldsymbol{U}_{E}
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$$
\begin{aligned}
f \boldsymbol{k} \times \boldsymbol{u}_{E} & =\frac{1}{\rho_{0}} \frac{\partial \boldsymbol{\tau}}{\partial z} \\
f \boldsymbol{k} \times \int_{-h}^{0} \boldsymbol{u}_{E} d z & =\frac{1}{\rho_{0}}(\boldsymbol{\tau}(z=0)-\boldsymbol{\tau}(z=-h))
\end{aligned}
$$

- vertically integrated velocity

$$
\boldsymbol{U}=\int_{-h}^{0} \boldsymbol{u} d z=\int_{-h}^{0}\left(\boldsymbol{u}_{G}+\boldsymbol{u}_{E}\right) d z=\boldsymbol{U}_{G}+\boldsymbol{U}_{E}
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f \boldsymbol{k} \times \int_{-h}^{0} \boldsymbol{u}_{E} d z & =\frac{1}{\rho_{0}}(\boldsymbol{\tau}(z=0)-\boldsymbol{\tau}(z=-h)) \\
f \boldsymbol{k} \times \boldsymbol{U}_{E} & =\frac{1}{\rho_{0}}\left(\boldsymbol{\tau}^{a}-\boldsymbol{\tau}_{b}\right) \\
\boldsymbol{U}_{E} & =-\frac{1}{f \rho_{0}} \boldsymbol{k} \times\left(\boldsymbol{\tau}^{a}-\boldsymbol{\tau}_{b}\right)
\end{aligned}
$$

with surface wind stress $\tau^{a}$ and bottom stress $\tau_{b}$

- vertically integrated velocity

$$
\boldsymbol{U}=\int_{-h}^{0} \boldsymbol{u} d z=\int_{-h}^{0}\left(\boldsymbol{u}_{G}+\boldsymbol{u}_{E}\right) d z=\boldsymbol{U}_{G}+\boldsymbol{U}_{E}
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\boldsymbol{U}_{E} & =-\frac{1}{f \rho_{0}} \boldsymbol{k} \times\left(\boldsymbol{\tau}^{a}-\boldsymbol{\tau}_{b}\right)
\end{aligned}
$$

with surface wind stress $\tau^{a}$ and bottom stress $\tau_{b}$

- split $\boldsymbol{U}_{E}$ into surface and bottom Ekman transport
- vertically integrated velocity $\boldsymbol{U}=\boldsymbol{U}_{G}+\boldsymbol{U}_{E}$ with geostrophic transport $\boldsymbol{U}_{G}$ and Ekman transport $\boldsymbol{U}_{E}$ given by

$$
\boldsymbol{U}_{E}=-\frac{1}{f \rho_{0}} \boldsymbol{k} \times\left(\tau^{a}-\boldsymbol{\tau}_{b}\right)
$$

with surface wind stress $\tau^{a}$ and bottom stress $\tau_{b}$

- vertically integrated velocity $\boldsymbol{U}=\boldsymbol{U}_{G}+\boldsymbol{U}_{E}$ with geostrophic transport $\boldsymbol{U}_{G}$ and Ekman transport $\boldsymbol{U}_{E}$ given by

$$
\boldsymbol{U}_{E}=-\frac{1}{f \rho_{0}} \boldsymbol{k} \times\left(\boldsymbol{\tau}^{a}-\boldsymbol{\tau}_{b}\right) \equiv \boldsymbol{U}_{E}^{\text {top }}+\boldsymbol{U}_{E}^{b o t}
$$

with surface wind stress $\tau^{a}$ and bottom stress $\tau_{b}$

- split into surface Ekman transport in surface Ekman layer

$$
\boldsymbol{U}_{E}^{\text {top }}=-\frac{1}{f \rho_{0}} \boldsymbol{k} \times \boldsymbol{\tau}^{\text {a }}
$$

orthogonal to wind stress direction (to the right for $f>0$ ) does not depend on parameterisation of $\tau$ in the interior

- vertically integrated velocity $\boldsymbol{U}=\boldsymbol{U}_{G}+\boldsymbol{U}_{E}$ with geostrophic transport $\boldsymbol{U}_{G}$ and Ekman transport $\boldsymbol{U}_{E}$ given by

$$
\boldsymbol{U}_{E}=-\frac{1}{f \rho_{0}} \boldsymbol{k} \times\left(\tau^{a}-\tau_{b}\right) \equiv \boldsymbol{U}_{E}^{\text {top }}+\boldsymbol{U}_{E}^{\text {bot }}
$$

with surface wind stress $\tau^{a}$ and bottom stress $\tau_{b}$

- split into surface Ekman transport in surface Ekman layer

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\boldsymbol{U}_{E}^{\text {top }}=-\frac{1}{f \rho_{0}} \boldsymbol{k} \times \boldsymbol{\tau}^{a}
$$

orthogonal to wind stress direction (to the right for $f>0$ ) does not depend on parameterisation of $\tau$ in the interior

- and bottom Ekman transport in bottom Ekman layer

$$
\boldsymbol{U}_{E}^{b o t}=\frac{1}{f \rho_{0}} \boldsymbol{k} \times \boldsymbol{\tau}_{b}
$$

depends on parameterisation of $\tau$ in the interior

- Elementarstromsystem
- $\boldsymbol{u}=\boldsymbol{u}_{G}+\boldsymbol{u}_{E}\left(\right.$ and $\left.w=w_{G}+w_{E}\right)$
surface and bottom Ekman layers superimposed on geostrophic flow

- zonal (left) and meridional component (right) of $\boldsymbol{\tau}^{a}$ in $10^{-2} \mathrm{~N} / \mathrm{m}^{2}$

- surface Ekman transport in surface Ekman layer

$$
\boldsymbol{U}_{E}^{t o p}=-\frac{1}{f \rho_{0}} \boldsymbol{k} \times \boldsymbol{\tau}^{a}
$$

orthogonal to wind stress direction (to the right for $f>0$ )

- zonal (left) and meridional component (right) of $\boldsymbol{\tau}^{a}$ in $10^{-2} \mathrm{~N} / \mathrm{m}^{2}$

- surface Ekman transport in surface Ekman layer

$$
\boldsymbol{U}_{E}^{\text {top }}=-\frac{1}{f \rho_{0}} \boldsymbol{k} \times \boldsymbol{\tau}^{a}
$$

orthogonal to wind stress direction (to the right for $f>0$ )

- equatorward in west wind region poleward in trade wind region
- zonal (left) and meridional component (right) of $\tau^{a}$ in $10^{-2} \mathrm{~N} / \mathrm{m}^{2}$
a)

b)

- surface Ekman transport in surface Ekman layer

$$
\boldsymbol{U}_{E}^{t o p}=-\frac{1}{f \rho_{0}} \boldsymbol{k} \times \boldsymbol{\tau}^{a}
$$

orthogonal to wind stress direction (to the right for $f>0$ )

- equatorward in west wind region poleward in trade wind region
- convergence between west wind and trade wind region
- divergence at high latitude and at equator


## Recapitulation

## Elementarstromsystem

Ekman transport

## Ekman pumping

Sverdrup transport
Sverdrup meets Ekman

Wind driven circulation
Western boundary currents

- integrating the continuity equation for $\boldsymbol{u}_{E}$ and $w_{E}$ from $z$ to $z=0$

$$
\boldsymbol{\nabla} \cdot \boldsymbol{u}_{E}+\frac{\partial w_{E}}{\partial z}=0
$$

yields the vertical Ekman velocity

$$
\int_{z}^{0} \nabla \cdot \boldsymbol{u}_{E} d z+w_{E}(z=0)-w_{E}(z)=0 \rightarrow w_{E}(z)=\nabla \cdot \int_{z}^{0} \boldsymbol{u}_{E} d z
$$

- integrating the continuity equation for $\boldsymbol{u}_{E}$ and $w_{E}$ from $z$ to $z=0$

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$$

- since $\boldsymbol{u}_{E} \approx 0$ below Ekman depth $D \approx 50 \mathrm{~m}$
$\left.w_{E}\right|_{z<-D} \approx \boldsymbol{\nabla} \cdot \int_{z<-D}^{0} \boldsymbol{u}_{E} d z=\boldsymbol{\nabla} \cdot \boldsymbol{U}_{E}^{\text {top }}=-\boldsymbol{\nabla} \cdot \frac{1}{f \rho_{0}} \boldsymbol{k} \times \boldsymbol{\tau}^{\boldsymbol{a}}$
with Ekman pumping $\left.w_{E}\right|_{z<-D}$
- integrating the continuity equation for $\boldsymbol{u}_{E}$ and $w_{E}$ from $z$ to $z=0$

$$
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with Ekman pumping $\left.w_{E}\right|_{z<-D}$
- Ekman pumping $w_{E}$ in $m$ per year

$$
\left.w_{E}\right|_{z<-D} \approx \nabla \cdot \boldsymbol{U}_{E}^{t o p}=\boldsymbol{k} \times \nabla \cdot \frac{\boldsymbol{\tau}^{a}}{\rho_{0} f}
$$

with Ekman depth $D \approx 50 \mathrm{~m}$ (depends on $A_{v}$ )


- Ekman transport $\boldsymbol{U}_{E}^{\text {top }}$ and pumping $w_{E}$ do not depend on $A_{V}$
- coastal upwelling

from Talley et al 2011
- equatorial upwelling

from Talley et al 2011


## Recapitulation

## Elementarstromsystem

Ekman transport
Ekman pumping
Sverdrup transport
Sverdrup meets Ekman

Wind driven circulation
Western boundary currents

- momentum equation in planetary geostrophic approximation

$$
f \boldsymbol{k} \times \boldsymbol{u}=-\frac{1}{\rho_{0}} \nabla_{h} p+\frac{1}{\rho_{0}} \frac{\partial \boldsymbol{\tau}}{\partial z} \text { with } \boldsymbol{k} \times \boldsymbol{u}=(-v, u, 0)
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$$

- neglect sea surface height $z=\zeta \rightarrow$ assume rigid lid at $z=0$
- assume flat bottom at $z=-h=$ const
- vertically integrate from bottom to surface

$$
\rho_{0} f \boldsymbol{k} \times \boldsymbol{U}=-\boldsymbol{\nabla}_{h} \int_{-h}^{0} p d z+\boldsymbol{\tau}_{a}-\boldsymbol{\tau}_{b}
$$

with transport $\boldsymbol{U}=\int_{-h}^{0} \boldsymbol{u} d z$, surface and bottom stress $\boldsymbol{\tau}_{a}$ and $\boldsymbol{\tau}_{b}$

- momentum equation in planetary geostrophic approximation

$$
f \boldsymbol{k} \times \boldsymbol{u}=-\frac{1}{\rho_{0}} \nabla_{h} p+\frac{1}{\rho_{0}} \frac{\partial \boldsymbol{\tau}}{\partial z} \text { with } \boldsymbol{k} \times \boldsymbol{u}=(-v, u, 0)
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\rho_{0} f \boldsymbol{k} \times \boldsymbol{U}=-\boldsymbol{\nabla}_{h} \int_{-h}^{0} p d z+\boldsymbol{\tau}_{a}-\boldsymbol{\tau}_{b}
$$

with transport $\boldsymbol{U}=\int_{-h}^{0} \boldsymbol{u} d z$, surface and bottom stress $\boldsymbol{\tau}_{a}$ and $\boldsymbol{\tau}_{b}$

- take curl and it follows the famous Sverdrup relation

$$
\rho_{0} \beta V=\boldsymbol{k} \times \boldsymbol{\nabla} \cdot\left(\boldsymbol{\tau}_{a}-\boldsymbol{\tau}_{b}\right)
$$

where $\boldsymbol{\tau}_{b}$ is often neglected

- depth integrated transport $V$ calculated from wind stress curl only
- since $\boldsymbol{\nabla}_{h} \cdot \boldsymbol{U}=0$ introduce volume transport streamfunction, with

$$
U=-\frac{\partial \psi}{\partial y} \quad, \quad V=\frac{\partial \psi}{\partial x} \quad \rightarrow \quad \boldsymbol{U}=\boldsymbol{k} \times \boldsymbol{\nabla} \psi
$$

transport $\boldsymbol{U}$ is parallel to contour lines of $\psi$

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transport $\boldsymbol{U}$ is parallel to contour lines of $\psi$

- $\psi$ determines transport perpendicular to or "across" section $A \rightarrow B$
- since $\boldsymbol{\nabla}_{h} \cdot \boldsymbol{U}=0$ introduce volume transport streamfunction, with

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transport $\boldsymbol{U}$ is parallel to contour lines of $\psi$

- $\psi$ determines transport perpendicular to or "across" section $A \rightarrow B$
- Sverdrup relation becomes

$$
\rho_{0} \beta V=\rho_{0} \beta \frac{\partial \psi}{\partial x}=\boldsymbol{k} \times \nabla \cdot \boldsymbol{\tau}_{a}
$$

for $\boldsymbol{\tau}_{b}=0$

- since $\boldsymbol{\nabla}_{h} \cdot \boldsymbol{U}=0$ introduce volume transport streamfunction, with

$$
U=-\frac{\partial \psi}{\partial y} \quad, \quad V=\frac{\partial \psi}{\partial x} \quad \rightarrow \quad \boldsymbol{U}=\boldsymbol{k} \times \boldsymbol{\nabla} \psi
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$$
\rho_{0} \beta V=\rho_{0} \beta \frac{\partial \psi}{\partial x}=\boldsymbol{k} \times \boldsymbol{\nabla} \cdot \boldsymbol{\tau}_{a}
$$

for $\boldsymbol{\tau}_{b}=0$

- integration from eastern boundary $\left(x=x_{E}\right)$ where $\psi\left(x_{E}\right)=0$

$$
\psi(x, y)=-\frac{1}{\rho_{0} \beta} \int_{x}^{x_{e}} \boldsymbol{k} \times \boldsymbol{\nabla} \cdot \boldsymbol{\tau}_{a} d x
$$

- $\psi\left(x_{E}\right)=0$ along east eastern boundary but not at western boundary $\rightarrow$ western boundary current not included
- $\psi=-1 /\left(\rho_{0} \beta\right) \int_{x}^{x_{e}} \boldsymbol{k} \times \boldsymbol{\nabla} \cdot \boldsymbol{\tau}^{a} d x$ from realistic wind stress in $10^{6} \mathrm{~m}^{3} / \mathrm{s} \equiv 1 \mathrm{~Sv}$

- $\psi$ in a global state estimate in $10^{6} \mathrm{~m}^{3} / \mathrm{s} \equiv 1 \mathrm{~Sv}$

- Streamfunction $\psi$ in $S v=10^{6} \mathrm{~m}^{3} / \mathrm{s}$ from simple Sverdrup relation
- Streamfunction $\psi$ for a realistic model of the Atlantic Ocean

b)

- simple Sverdrup relation works surprisingly well


## Recapitulation

# Elementarstromsystem <br> Ekman transport <br> Ekman pumping <br> Sverdrup transport 

Sverdrup meets Ekman

Wind driven circulation
Western boundary currents

- vertically integrated momentum equation

$$
\begin{aligned}
-\rho_{0} f V & =-\frac{\partial}{\partial x} \int_{-h}^{0} p d z+\tau_{a}^{x} \equiv-\frac{\partial P}{\partial x}+\tau_{a}^{x} \\
\rho_{0} f U & =-\frac{\partial}{\partial y} \int_{-h}^{0} p d z+\tau_{a}^{y} \equiv-\frac{\partial P}{\partial y}+\tau_{a}^{y}
\end{aligned}
$$

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\end{aligned}
$$

- split in Ekman transport $\boldsymbol{U}_{E}$ und geostrophic transport $\boldsymbol{U}_{G}$

$$
\begin{aligned}
-\rho_{0} f V \equiv-\rho_{0} f\left(V_{G}+V_{E}\right) & =-\frac{\partial P}{\partial x}+\tau_{a}^{x} \\
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\rho_{0} f U \equiv \rho_{0} f\left(U_{G}+U_{E}\right) & =-\frac{\partial P}{\partial y}+\tau_{a}^{y}
\end{aligned}
$$

- with Ekman transport

$$
-\rho_{0} f V_{E}=\tau_{a}^{x}, \rho_{0} f U_{E}=\tau_{a}^{y} \rightarrow \rho_{0} f \boldsymbol{k} \times \boldsymbol{U}_{E}=\boldsymbol{\tau}_{a} \rightarrow \rho_{0} f \boldsymbol{U}_{E}=-\boldsymbol{k} \times \boldsymbol{\tau}_{a}
$$

- vertically integrated momentum equation

$$
\begin{aligned}
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\end{aligned}
$$

- with Ekman transport

$$
-\rho_{0} f V_{E}=\tau_{a}^{x}, \rho_{0} f U_{E}=\tau_{a}^{y} \rightarrow \rho_{0} f \boldsymbol{k} \times \boldsymbol{U}_{E}=\boldsymbol{\tau}_{a} \rightarrow \rho_{0} f \boldsymbol{U}_{E}=-\boldsymbol{k} \times \boldsymbol{\tau}_{a}
$$

- and with geostrophic transport

$$
-\rho_{0} f V_{G}=-\frac{\partial P}{\partial x}, \rho_{0} f U_{G}=-\frac{\partial P}{\partial y} \rightarrow \rho_{0} f \boldsymbol{U}_{G}=\boldsymbol{k} \times \nabla_{h} P
$$

- vertically integrated momentum equation

$$
\begin{aligned}
-\rho_{0} f V & =-\frac{\partial}{\partial x} \int_{-h}^{0} p d z+\tau_{a}^{x} \equiv-\frac{\partial P}{\partial x}+\tau_{a}^{x} \\
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$$
-\rho_{0} f V_{E}=\tau_{a}^{x}, \rho_{0} f U_{E}=\tau_{a}^{y} \rightarrow \rho_{0} f \boldsymbol{k} \times \boldsymbol{U}_{E}=\boldsymbol{\tau}_{a} \rightarrow \rho_{0} f \boldsymbol{U}_{E}=-\boldsymbol{k} \times \boldsymbol{\tau}_{a}
$$

- and with geostrophic transport

$$
-\rho_{0} f V_{G}=-\frac{\partial P}{\partial x}, \rho_{0} f U_{G}=-\frac{\partial P}{\partial y} \rightarrow \rho_{0} f \boldsymbol{U}_{G}=\boldsymbol{k} \times \nabla_{h} P
$$

- Ekman transport + geostr. transport $=$ Sverdrup transport
- Ekman transport + geostr. transport $=$ Sverdrup transport
- with Ekman transport

$$
-\rho_{0} f V_{E}=\tau_{a}^{x} \quad, \quad \rho_{0} f U_{E}=\tau_{a}^{y} \quad, \quad \rho_{0} f \boldsymbol{U}_{E}=-\boldsymbol{k} \times \boldsymbol{\tau}_{a}
$$

- and geostrophic transport

$$
-\rho_{0} f V_{G}=-\frac{\partial P}{\partial x} \quad, \quad \rho_{0} f U_{G}=-\frac{\partial P}{\partial y}, \quad \rho_{0} f \boldsymbol{U}_{G}=\boldsymbol{k} \times \nabla_{h} P
$$

- Ekman transport + geostr. transport $=$ Sverdrup transport
- with Ekman transport

$$
-\rho_{0} f V_{E}=\tau_{a}^{x} \quad, \quad \rho_{0} f U_{E}=\tau_{a}^{y} \quad, \quad \rho_{0} f \boldsymbol{U}_{E}=-\boldsymbol{k} \times \boldsymbol{\tau}_{a}
$$

- and geostrophic transport

$$
-\rho_{0} f V_{G}=-\frac{\partial P}{\partial x}, \quad \rho_{0} f U_{G}=-\frac{\partial P}{\partial y} \quad, \quad \rho_{0} f \boldsymbol{U}_{G}=\boldsymbol{k} \times \nabla_{h} P
$$

- both transports are divergent

$$
\nabla_{h} \cdot \boldsymbol{U}_{E}=-\nabla_{h} \cdot \boldsymbol{k} \times \frac{\boldsymbol{\tau}_{a}}{\rho_{0} f}=\boldsymbol{k} \times \nabla_{h} \cdot \frac{\boldsymbol{\tau}_{a}}{\rho_{0} f}=w_{E}
$$

- Ekman transport + geostr. transport $=$ Sverdrup transport
- with Ekman transport

$$
-\rho_{0} f V_{E}=\tau_{a}^{\times} \quad, \quad \rho_{0} f U_{E}=\tau_{a}^{y} \quad, \quad \rho_{0} f \boldsymbol{U}_{E}=-\boldsymbol{k} \times \boldsymbol{\tau}_{a}
$$

- and geostrophic transport

$$
-\rho_{0} f V_{G}=-\frac{\partial P}{\partial x}, \quad \rho_{0} f U_{G}=-\frac{\partial P}{\partial y} \quad, \quad \rho_{0} f \boldsymbol{U}_{G}=\boldsymbol{k} \times \nabla_{h} P
$$

- both transports are divergent

$$
\begin{aligned}
& \boldsymbol{\nabla}_{h} \cdot \boldsymbol{U}_{E}=-\boldsymbol{\nabla}_{h} \cdot \boldsymbol{k} \times \frac{\boldsymbol{\tau}_{a}}{\rho_{0} f}=\boldsymbol{k} \times \boldsymbol{\nabla}_{h} \cdot \frac{\boldsymbol{\tau}_{a}}{\rho_{0} f}=w_{E} \\
& \boldsymbol{\nabla}_{h} \cdot \boldsymbol{U}_{G}=-\frac{\partial}{\partial x}\left(\frac{\partial P}{\partial y} \frac{1}{\rho_{0} f}\right)+\frac{\partial}{\partial y}\left(\frac{\partial P}{\partial x} \frac{1}{\rho_{0} f}\right)=\frac{\partial P}{\partial x} \frac{\partial}{\partial y}\left(\frac{1}{\rho_{0} f}\right)
\end{aligned}
$$

- Ekman transport + geostr. transport $=$ Sverdrup transport
- with Ekman transport

$$
-\rho_{0} f V_{E}=\tau_{a}^{x} \quad, \quad \rho_{0} f U_{E}=\tau_{a}^{y} \quad, \quad \rho_{0} f \boldsymbol{U}_{E}=-\boldsymbol{k} \times \boldsymbol{\tau}_{a}
$$

- and geostrophic transport

$$
-\rho_{0} f V_{G}=-\frac{\partial P}{\partial x} \quad, \quad \rho_{0} f U_{G}=-\frac{\partial P}{\partial y}, \quad \rho_{0} f \boldsymbol{U}_{G}=\boldsymbol{k} \times \nabla_{h} P
$$

- both transports are divergent

$$
\begin{aligned}
\boldsymbol{\nabla}_{h} \cdot \boldsymbol{U}_{E} & =-\boldsymbol{\nabla}_{h} \cdot \boldsymbol{k} \times \frac{\boldsymbol{\tau}_{a}}{\rho_{0} f}=\boldsymbol{k} \times \boldsymbol{\nabla}_{h} \cdot \frac{\boldsymbol{\tau}_{a}}{\rho_{0} f}=w_{E} \\
\boldsymbol{\nabla}_{h} \cdot \boldsymbol{U}_{G} & =-\frac{\partial}{\partial x}\left(\frac{\partial P}{\partial y} \frac{1}{\rho_{0} f}\right)+\frac{\partial}{\partial y}\left(\frac{\partial P}{\partial x} \frac{1}{\rho_{0} f}\right)=\frac{\partial P}{\partial x} \frac{\partial}{\partial y}\left(\frac{1}{\rho_{0} f}\right) \\
& =-\frac{1}{\rho_{0} f^{2}} \frac{d f}{d y} \frac{\partial P}{\partial x}=-\frac{\beta}{\rho_{0} f^{2}} \frac{\partial P}{\partial x}
\end{aligned}
$$

- Ekman transport + geostr. transport $=$ Sverdrup transport
- with Ekman transport

$$
-\rho_{0} f V_{E}=\tau_{a}^{x} \quad, \quad \rho_{0} f U_{E}=\tau_{a}^{y} \quad, \quad \rho_{0} f \boldsymbol{U}_{E}=-\boldsymbol{k} \times \boldsymbol{\tau}_{a}
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- and geostrophic transport

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-\rho_{0} f V_{G}=-\frac{\partial P}{\partial x} \quad, \quad \rho_{0} f U_{G}=-\frac{\partial P}{\partial y}, \quad \rho_{0} f \boldsymbol{U}_{G}=\boldsymbol{k} \times \nabla_{h} P
$$

- both transports are divergent

$$
\begin{aligned}
\boldsymbol{\nabla}_{h} \cdot \boldsymbol{U}_{E} & =-\boldsymbol{\nabla}_{h} \cdot \boldsymbol{k} \times \frac{\boldsymbol{\tau}_{a}}{\rho_{0} f}=\boldsymbol{k} \times \boldsymbol{\nabla}_{h} \cdot \frac{\boldsymbol{\tau}_{a}}{\rho_{0} f}=w_{E} \\
\boldsymbol{\nabla}_{h} \cdot \boldsymbol{U}_{G} & =-\frac{\partial}{\partial x}\left(\frac{\partial P}{\partial y} \frac{1}{\rho_{0} f}\right)+\frac{\partial}{\partial y}\left(\frac{\partial P}{\partial x} \frac{1}{\rho_{0} f}\right)=\frac{\partial P}{\partial x} \frac{\partial}{\partial y}\left(\frac{1}{\rho_{0} f}\right) \\
& =-\frac{1}{\rho_{0} f^{2}} \frac{d f}{d y} \frac{\partial P}{\partial x}=-\frac{\beta}{\rho_{0} f^{2}} \frac{\partial P}{\partial x}=-\frac{\beta}{f} V_{G}
\end{aligned}
$$

- Ekman transport + geostr. transport $=$ Sverdrup transport
- with Ekman transport

$$
-\rho_{0} f V_{E}=\tau_{a}^{x} \quad, \quad \rho_{0} f U_{E}=\tau_{a}^{y} \quad, \quad \rho_{0} f \boldsymbol{U}_{E}=-\boldsymbol{k} \times \boldsymbol{\tau}_{a}
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\boldsymbol{\nabla}_{h} \cdot \boldsymbol{U}_{E} & =-\boldsymbol{\nabla}_{h} \cdot \boldsymbol{k} \times \frac{\boldsymbol{\tau}_{a}}{\rho_{0} f}=\boldsymbol{k} \times \boldsymbol{\nabla}_{h} \cdot \frac{\boldsymbol{\tau}_{a}}{\rho_{0} f}=w_{E} \\
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& =-\frac{1}{\rho_{0} f^{2}} \frac{d f}{d y} \frac{\partial P}{\partial x}=-\frac{\beta}{\rho_{0} f^{2}} \frac{\partial P}{\partial x}=-\frac{\beta}{f} V_{G}
\end{aligned}
$$

- but the total transport $\boldsymbol{U}=\boldsymbol{U}_{E}+\boldsymbol{U}_{G}$ is non-divergent

$$
\boldsymbol{\nabla}_{h} \cdot \boldsymbol{U}=0 \quad \rightarrow \quad w_{E}^{\text {top }}=\frac{\beta}{f} V_{G}
$$

Ekman pumping generates southward geostr. transport (for $f_{\equiv}>0$ )

- Ekman pumping generates southward geostr. transport (for $f>0$ )

from Talley et al 2011
- Sverdrup relation follows from potential vorticity conservation
- potential vorticity equation for a single layer

$$
\frac{D q}{D t}=0 \quad, \quad q=\frac{\zeta+f}{h} \text { or } q \approx \zeta-\frac{f_{0}}{H} h+f
$$

$q$ is conserved for fluid parcels in single layer

- $w_{E}$ lead to vortex stretching and meridional motion



## Recapitulation

## Elementarstromsystem <br> Ekman transport <br> Ekman pumping <br> Sverdrup transport <br> Sverdrup meets Ekman

Wind driven circulation
Western boundary currents

- momentum equation in planetary geostrophic approximation

$$
f \boldsymbol{k} \times \boldsymbol{u}=-\boldsymbol{\nabla}_{h} p+\frac{\partial \boldsymbol{\tau}}{\partial z}+A_{h} \boldsymbol{\nabla}_{h}^{2} \boldsymbol{u}-R \boldsymbol{u}
$$

with stress vector $\boldsymbol{\tau}$ connecting to surface wind stress with lateral friction related to the lateral turbulent viscosity $A_{h}$ and with turbulent Rayleigh (bottom) friction related to $R$

- momentum equation in planetary geostrophic approximation

$$
f \boldsymbol{k} \times \boldsymbol{u}=-\nabla_{h} p+\frac{\partial \boldsymbol{\tau}}{\partial z}+A_{h} \boldsymbol{\nabla}_{h}^{2} \boldsymbol{u}-R \boldsymbol{u}
$$

with stress vector $\boldsymbol{\tau}$ connecting to surface wind stress with lateral friction related to the lateral turbulent viscosity $A_{h}$ and with turbulent Rayleigh (bottom) friction related to $R$

- vertically integrating from flat bottom to surface (assume $\boldsymbol{\tau}_{b}=0$ )

$$
f \boldsymbol{k} \times \int_{-h}^{0} \boldsymbol{u} d z=-\int_{-h}^{0} \nabla_{h} p d z+\boldsymbol{\tau}_{a}+\int_{-h}^{0}\left(A_{h} \nabla_{h}^{2}-R\right) \boldsymbol{u} d z
$$

- momentum equation in planetary geostrophic approximation

$$
f \boldsymbol{k} \times \boldsymbol{u}=-\nabla_{h} p+\frac{\partial \boldsymbol{\tau}}{\partial z}+A_{h} \boldsymbol{\nabla}_{h}^{2} \boldsymbol{u}-R \boldsymbol{u}
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$$

- for $h=$ const vertical integration and $\nabla$ commute

$$
f \boldsymbol{k} \times \boldsymbol{U}=-\boldsymbol{\nabla}_{h} \int_{-h}^{0} p d z+\boldsymbol{\tau}_{a}+\left(A_{h} \boldsymbol{\nabla}_{h}^{2}-R\right) \boldsymbol{U}
$$

with transport $\boldsymbol{U}=\int_{-h}^{0} \boldsymbol{u} d z$

- momentum equation in planetary geostrophic approximation

$$
f \boldsymbol{k} \times \boldsymbol{u}=-\nabla_{h} p+\frac{\partial \boldsymbol{\tau}}{\partial z}+A_{h} \boldsymbol{\nabla}_{h}^{2} \boldsymbol{u}-R \boldsymbol{u}
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$$

- for $h=$ const vertical integration and $\nabla$ commute

$$
f \boldsymbol{k} \times \boldsymbol{U}=-\boldsymbol{\nabla}_{h} \int_{-h}^{0} p d z+\boldsymbol{\tau}_{a}+\left(A_{h} \boldsymbol{\nabla}_{h}^{2}-R\right) \boldsymbol{U}
$$

with transport $\boldsymbol{U}=\int_{-h}^{0} \boldsymbol{u} d z$

- use transport streamfunction $\psi$ with $\boldsymbol{U}=\boldsymbol{k} \times \boldsymbol{\nabla} \psi$

$$
-f \nabla_{h} \psi=-\nabla_{h} \int_{-h}^{0} p d z+\tau_{a}+\left(A_{h} \nabla_{h}^{2}-R\right) \boldsymbol{k} \times \nabla \psi
$$

- vertically integrated momentum equation

$$
-f \nabla_{h} \psi=-\nabla_{h} \int_{-h}^{0} p d z+\tau_{a}+\left(A_{h} \nabla_{h}^{2}-R\right) \boldsymbol{k} \times \nabla \psi
$$

with transport $\boldsymbol{U}=\int_{-h}^{0} \boldsymbol{u d z}$ and streamfunction $\boldsymbol{U}=\boldsymbol{k} \times \boldsymbol{\nabla} \psi$

- vertically integrated momentum equation

$$
-f \nabla_{h} \psi=-\nabla_{h} \int_{-h}^{0} p d z+\tau_{a}+\left(A_{h} \nabla_{h}^{2}-R\right) \boldsymbol{k} \times \nabla \psi
$$

with transport $\boldsymbol{U}=\int_{-h}^{0} \boldsymbol{u} d z$ and streamfunction $\boldsymbol{U}=\boldsymbol{k} \times \boldsymbol{\nabla} \psi$

- now take curl $(\boldsymbol{k} \times \nabla)$. of momentum equation

$$
-(\boldsymbol{k} \times \nabla) \cdot f \nabla_{h} \psi=\boldsymbol{k} \times \boldsymbol{\nabla} \cdot \boldsymbol{\tau}_{a}+\left(A_{h} \nabla_{h}^{2}-R\right)(\boldsymbol{k} \times \nabla) \cdot(\boldsymbol{k} \times \nabla) \psi
$$

since $(\boldsymbol{k} \times \boldsymbol{\nabla}) \cdot \nabla_{h} \int_{-h}^{0} p d z=0$

- vertically integrated momentum equation

$$
-f \nabla_{h} \psi=-\nabla_{h} \int_{-h}^{0} p d z+\tau_{a}+\left(A_{h} \nabla_{h}^{2}-R\right) \boldsymbol{k} \times \nabla \psi
$$

with transport $\boldsymbol{U}=\int_{-h}^{0} \boldsymbol{u} d z$ and streamfunction $\boldsymbol{U}=\boldsymbol{k} \times \boldsymbol{\nabla} \psi$

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$$

$$
\text { since }(\boldsymbol{k} \times \boldsymbol{\nabla}) \cdot \boldsymbol{\nabla}_{h} \int_{-h}^{0} p d z=0
$$

- with

$$
-(\boldsymbol{k} \times \nabla) \cdot f \nabla_{h} \psi=-f(\boldsymbol{k} \times \nabla) \cdot \nabla_{h} \psi-\nabla_{h} \psi \cdot(\boldsymbol{k} \times \nabla) f=
$$

- vertically integrated momentum equation

$$
-f \nabla_{h} \psi=-\nabla_{h} \int_{-h}^{0} p d z+\tau_{a}+\left(A_{h} \nabla_{h}^{2}-R\right) \boldsymbol{k} \times \nabla \psi
$$

with transport $\boldsymbol{U}=\int_{-h}^{0} \boldsymbol{u} d z$ and streamfunction $\boldsymbol{U}=\boldsymbol{k} \times \boldsymbol{\nabla} \psi$

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$$
-(\boldsymbol{k} \times \nabla) \cdot f \nabla_{h} \psi=\boldsymbol{k} \times \boldsymbol{\nabla} \cdot \boldsymbol{\tau}_{a}+\left(A_{h} \nabla_{h}^{2}-R\right)(\boldsymbol{k} \times \nabla) \cdot(\boldsymbol{k} \times \nabla) \psi
$$

$$
\text { since }(\boldsymbol{k} \times \boldsymbol{\nabla}) \cdot \boldsymbol{\nabla}_{h} \int_{-h}^{0} p d z=0
$$

- with

$$
-(k \times \nabla) \cdot f \nabla_{h} \psi=-f(k \times \nabla) \cdot \nabla_{h} \psi-\nabla_{h} \psi \cdot(k \times \nabla) f=\beta \frac{\partial \psi}{\partial x}
$$

- vertically integrated momentum equation

$$
-f \nabla_{h} \psi=-\nabla_{h} \int_{-h}^{0} p d z+\tau_{a}+\left(A_{h} \nabla_{h}^{2}-R\right) \boldsymbol{k} \times \nabla \psi
$$

with transport $\boldsymbol{U}=\int_{-h}^{0} \boldsymbol{u} d z$ and streamfunction $\boldsymbol{U}=\boldsymbol{k} \times \boldsymbol{\nabla} \psi$

- now take curl $(\boldsymbol{k} \times \nabla)$. of momentum equation
$-(\boldsymbol{k} \times \boldsymbol{\nabla}) \cdot f \boldsymbol{\nabla}_{h} \psi=\boldsymbol{k} \times \boldsymbol{\nabla} \cdot \boldsymbol{\tau}_{a}+\left(A_{h} \boldsymbol{\nabla}_{h}^{2}-R\right)(\boldsymbol{k} \times \boldsymbol{\nabla}) \cdot(\boldsymbol{k} \times \boldsymbol{\nabla}) \psi$ since $(\boldsymbol{k} \times \boldsymbol{\nabla}) \cdot \nabla_{h} \int_{-h}^{0} p d z=0$
- with
$-(\boldsymbol{k} \times \boldsymbol{\nabla}) \cdot f \nabla_{h} \psi=-f(\boldsymbol{k} \times \boldsymbol{\nabla}) \cdot \nabla_{h} \psi-\nabla_{h} \psi \cdot(\boldsymbol{k} \times \nabla) f=\beta \frac{\partial \psi}{\partial x}$
and with $(\boldsymbol{k} \times \boldsymbol{\nabla}) \cdot(\boldsymbol{k} \times \boldsymbol{\nabla}) \psi=\boldsymbol{\nabla}_{h}^{2} \psi$
- vertically integrated momentum equation

$$
-f \nabla_{h} \psi=-\nabla_{h} \int_{-h}^{0} p d z+\tau_{a}+\left(A_{h} \nabla_{h}^{2}-R\right) \boldsymbol{k} \times \nabla \psi
$$

with transport $\boldsymbol{U}=\int_{-h}^{0} \boldsymbol{u} d z$ and streamfunction $\boldsymbol{U}=\boldsymbol{k} \times \boldsymbol{\nabla} \psi$

- now take curl $(\boldsymbol{k} \times \nabla)$. of momentum equation
$-(\boldsymbol{k} \times \boldsymbol{\nabla}) \cdot f \boldsymbol{\nabla}_{h} \psi=\boldsymbol{k} \times \boldsymbol{\nabla} \cdot \boldsymbol{\tau}_{a}+\left(A_{h} \boldsymbol{\nabla}_{h}^{2}-R\right)(\boldsymbol{k} \times \boldsymbol{\nabla}) \cdot(\boldsymbol{k} \times \boldsymbol{\nabla}) \psi$ since $(\boldsymbol{k} \times \boldsymbol{\nabla}) \cdot \nabla_{h} \int_{-h}^{0} p d z=0$
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$-(\boldsymbol{k} \times \boldsymbol{\nabla}) \cdot f \nabla_{h} \psi=-f(\boldsymbol{k} \times \boldsymbol{\nabla}) \cdot \nabla_{h} \psi-\nabla_{h} \psi \cdot(\boldsymbol{k} \times \nabla) f=\beta \frac{\partial \psi}{\partial x}$
and with $(\boldsymbol{k} \times \boldsymbol{\nabla}) \cdot(\boldsymbol{k} \times \boldsymbol{\nabla}) \psi=\nabla_{h}^{2} \psi$
- the Stommel/Munk equation for flat bottom follows as

$$
\beta \frac{\partial \psi}{\partial x}=\boldsymbol{k} \times \boldsymbol{\nabla} \cdot \boldsymbol{\tau}_{a}+\left(A_{h} \nabla_{h}^{2}-R\right) \nabla_{h}^{2} \psi
$$

first part identical to Sverdrup relation, friction related to $A_{h}$ and $R$ closes circulation at western boundary

- numerical solution of Stommel's equation

$$
\beta \frac{\partial \psi}{\partial x}=\boldsymbol{k} \times \nabla \cdot \boldsymbol{\tau}_{a}-R \nabla_{h}^{2} \psi
$$

with realistic wind stress $\tau_{a}\left(\right.$ and $\left.A_{h}=0\right)$


- Henry Melson Stommel, * 1920 in Wilmington (USA) $\dagger 1992$ in Boston (USA), oceanographer.
- consider a wind stress of the form $\tau_{a}=\left(-\tau_{0} \cos \frac{\pi y}{B}, 0\right)$
with $A_{h}=0 \rightarrow$ Stommel's equation (left)
and $R=0 \rightarrow$ Munk's equation (right)

- boundary layer scaling

$$
\beta \frac{\partial \psi}{\partial x}=\boldsymbol{k} \times \boldsymbol{\nabla} \cdot \boldsymbol{\tau}_{a}+\left(A_{h} \boldsymbol{\nabla}_{h}^{2}-R\right) \nabla_{h}^{2} \psi
$$

- balance bottom friction $R \nabla_{h}^{2} \psi$ and planetary vorticity $\beta \partial \psi / \partial x$

$$
\begin{aligned}
\beta \psi / L & \sim R \psi / L^{2} \\
L & \sim R / \beta
\end{aligned}
$$

Stommel's boundary layer with $R / \beta \approx 50-100 \mathrm{~km}$

- boundary layer scaling

$$
\beta \frac{\partial \psi}{\partial x}=\boldsymbol{k} \times \boldsymbol{\nabla} \cdot \boldsymbol{\tau}_{a}+\left(A_{h} \boldsymbol{\nabla}_{h}^{2}-R\right) \boldsymbol{\nabla}_{h}^{2} \psi
$$

- balance bottom friction $R \nabla_{h}^{2} \psi$ and planetary vorticity $\beta \partial \psi / \partial x$

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\beta \psi / L & \sim R \psi / L^{2} \\
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Stommel's boundary layer with $R / \beta \approx 50-100 \mathrm{~km}$

- balance lateral friction $A_{h} \boldsymbol{\nabla}_{h}^{4} \psi$ and planetary vorticity $\beta \partial \psi / \partial x$

$$
\begin{aligned}
\beta \psi / L & \sim A_{h} \psi / L^{4} \\
L & \sim\left(A_{h} / \beta\right)^{1 / 3}
\end{aligned}
$$

Munk's boundary layer with $\left(A_{h} / \beta\right)^{1 / 3}$

- $\left(A_{h} / \beta\right)^{1 / 3}$ is often used to choose value for $A_{h}$ in numerical models
- why is the western boundary current in the west?
- dominant balance in the western boundary current regime

$$
\beta \frac{\partial \psi}{\partial x}=\beta V \approx \boldsymbol{k} \times \nabla \cdot \boldsymbol{\tau}_{a}-R \nabla_{h}^{2} \psi \approx-R \frac{\partial^{2} \psi}{\partial x^{2}}=-R \frac{\partial V}{\partial x}
$$

between bottom friction and change in planetary vorticity

- why is the western boundary current in the west?
- dominant balance in the western boundary current regime

$$
\beta \frac{\partial \psi}{\partial x}=\beta V \approx \boldsymbol{k} \times \boldsymbol{\nabla} \cdot \boldsymbol{\tau}_{a}-R \nabla_{h}^{2} \psi \approx-R \frac{\partial^{2} \psi}{\partial x^{2}}=-R \frac{\partial V}{\partial x}
$$

between bottom friction and change in planetary vorticity

- since $V<0$ in the interior of the subtropical gyre
$V>0$ in the western boundary $\rightarrow \beta V>0 \rightarrow R \partial V / \partial x<0$
- why is the western boundary current in the west?
- dominant balance in the western boundary current regime

$$
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- since $V<0$ in the interior of the subtropical gyre
$V>0$ in the western boundary $\rightarrow \beta V>0 \rightarrow R \partial V / \partial x<0$
- for western boundary layer $V$ decreases to the east $\rightarrow \partial V / \partial x<0$
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- for eastern boundary layer $V$ increases to the east
$\rightarrow$ no eastern boundary layer
- why is the western boundary current in the west?
- dominant balance in the western boundary current regime

$$
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$$

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- westward Rossby waves propagate to the west
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$$
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- westward Rossby waves propagate to the west
- they are reflected at the western boundary as short Rossby waves with eastward group velocity
- why is the western boundary current in the west?
- dominant balance in the western boundary current regime

$$
\beta \frac{\partial \psi}{\partial x}=\beta V \approx \boldsymbol{k} \times \boldsymbol{\nabla} \cdot \boldsymbol{\tau}_{a}-R \nabla_{h}^{2} \psi \approx-R \frac{\partial^{2} \psi}{\partial x^{2}}=-R \frac{\partial V}{\partial x}
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between bottom friction and change in planetary vorticity

- since $V<0$ in the interior of the subtropical gyre
$V>0$ in the western boundary $\rightarrow \beta V>0 \rightarrow R \partial V / \partial x<0$
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- for eastern boundary layer $V$ increases to the east
$\rightarrow$ no eastern boundary layer
- westward Rossby waves propagate to the west
- they are reflected at the western boundary as short Rossby waves with eastward group velocity
- short Rossby waves are dissipated in the west and form the boundary current

- Schematic of the near-surface circulation (after Schmitz 1996). Subtropical gyres are red, subpolar and polar gyres blue equatorial gyres magenta, Antarctic Circumpolar Current is blue green lines represent exchange between basins and gyres

