# Dynamische und regionale Ozeanographie WS 2014/15

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# Lecture # 2

#### Recapitulation

Euler/Lagrange framework General conservation equation Continuity or mass conservation equation Salinity and salt conservation Momentum or Navier Stokes equation Heat and temperature equation Rotating earth

#### Approximations and simplifications

Boussinesq approximation Hydrostatic approximation

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Recapitulation



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Euler's relation

$$\frac{\delta C}{\delta t} \rightarrow \left(\frac{\partial}{\partial t}C\right)_{parcel} = \frac{\partial}{\partial t}C + \boldsymbol{u} \cdot \boldsymbol{\nabla}C \equiv \frac{D}{Dt}C$$

D/Dt = ∂/∂t + u · ∇ is often called 'material' or 'substantial' derivative

Recapitulation



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- local rate of change plus change implied by advection of fluid
- if DC/Dt = 0, property C of parcels does not change, it's conservative (but locally C might change in time)
- Lagrangian frameworks uses left hand side of DC/Dt
   Eulerian framework uses right hand side of DC/Dt
   both are equivalent but Eulerian framework is often more convenient

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# Recapitulation

# Euler/Lagrange framework

### General conservation equation

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# Approximations and simplifications

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- consider volume V, fixed in space and bounded by a surface A
- and a scalar fluid property C concentration
   (in units of C per kg sea water or ρC in units of C per m<sup>3</sup>)



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- conservation equation for property concentration C

$$\frac{\partial}{\partial t}\rho C = -\boldsymbol{\nabla} \cdot (\rho C \boldsymbol{u} + \boldsymbol{J}) + \boldsymbol{Q} \quad , \quad \rho \frac{DC}{Dt} = -\boldsymbol{\nabla} \cdot \boldsymbol{J} + \boldsymbol{Q}$$

flux form and parcel form



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general conservation law in flux form

$$\frac{\partial}{\partial t}\rho \boldsymbol{C} = -\boldsymbol{\nabla} \cdot (\rho \boldsymbol{C} \boldsymbol{u} + \boldsymbol{J}) + \boldsymbol{Q}$$

 $\blacktriangleright\,$  take C = 1( kg /kg sea water),  $\rightarrow\,\rho\,C$  becomes total mass per  $m^3$ 

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mass conservation or continuity equation

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possible to rewrite flux form (above) to parcel form

$$\frac{\partial \rho}{\partial t} + \boldsymbol{u} \cdot \boldsymbol{\nabla} \rho \equiv \frac{D \rho}{D t} = -\rho \boldsymbol{\nabla} \cdot \boldsymbol{u}$$

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• with specific volume  $v = 1/\rho$  continuity equation becomes

$$\frac{D\rho}{Dt} = \frac{D}{Dt}v^{-1} = -\frac{1}{v^2}\frac{Dv}{Dt} = -\frac{1}{v}\boldsymbol{\nabla}\cdot\boldsymbol{u}$$

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parcel form of continuity equation

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general conservation law in flux form

$$\frac{\partial}{\partial t}\rho C = -\boldsymbol{\nabla} \cdot (\rho C \boldsymbol{u} + \boldsymbol{J}) + Q$$

▶ salt conservation equation with C = S, Q = 0 but  $J = J_S$ 

$$\frac{\partial}{\partial t}\rho S = -\boldsymbol{\nabla} \cdot (\rho S \boldsymbol{u} + \boldsymbol{J}_S)$$

with salt flux  $J_S$  by molecular diffusion

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rewrite to parcel form given by

$$\rho \frac{\partial S}{\partial t} + S \frac{\partial \rho}{\partial t} = -\nabla \cdot \rho S \boldsymbol{u} - \nabla \cdot \boldsymbol{J}_{S}$$

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$$\rho \frac{DS}{Dt} = -\nabla \cdot \boldsymbol{J}_{S}$$

using continuity equation  $\partial \rho / \partial t = - \nabla \cdot \rho \boldsymbol{u}$  times S

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flux form and parcel form

• flux form for momentum component  $u_i = C$ 

$$\frac{\partial}{\partial t}\rho u_i = -\boldsymbol{\nabla}\cdot\left(\rho u_i \boldsymbol{u} + \boldsymbol{J}^{(i)}\right) + Q_i$$

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• in vector form and with (stress) tensor  $-\Pi_{ji} = J_j^{(i)}$ 

$$\rho \frac{D\boldsymbol{u}}{Dt} = \boldsymbol{\nabla} \cdot \boldsymbol{\Pi} + \boldsymbol{Q}$$

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$$\rho \frac{D\boldsymbol{u}}{Dt} = \boldsymbol{\nabla} \cdot \boldsymbol{\Pi} + \boldsymbol{Q}$$

▶  $\nabla \cdot \Pi$  and Q are forces (per volume) acting on the water parcel

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$$\rho \frac{D \boldsymbol{u}}{D t} = \boldsymbol{\nabla} \cdot \boldsymbol{\Pi} + \boldsymbol{f}^{\boldsymbol{v}} = -\boldsymbol{\nabla} \boldsymbol{p} + \boldsymbol{\nabla} \cdot \boldsymbol{\Sigma} + \boldsymbol{f}^{\boldsymbol{v}}$$

with the (mechanical) pressure as the mean normal inward stress

$$p = -\frac{1}{3} (\Pi_{11} + \Pi_{22} + \Pi_{33}) = -\frac{1}{3} \Pi_{ii} = -\frac{1}{3} \text{tr } \Pi$$

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balance of momentum in parcel form

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Newtonian fluid: relation between friction and velocity shear

$$\Sigma_{ij} = \nu \left( \frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} - \frac{2}{3} \frac{\partial u_\ell}{\partial x_\ell} \delta_{ij} \right)$$

with the (dynamical) viscosity  $\nu$ 

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with the (dynamical) viscosity  $\nu$ 

• Navier-Stokes equation for Newtonian fluid (and constant  $\nu$ )

$$\rho \frac{D\boldsymbol{u}}{D\boldsymbol{t}} = -\boldsymbol{\nabla}\boldsymbol{p} + \nu \boldsymbol{\nabla}^2 \boldsymbol{u} + \frac{\nu}{3} \boldsymbol{\nabla} (\boldsymbol{\nabla} \cdot \boldsymbol{u}) + \boldsymbol{f}^{\nu}$$

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 $\blacktriangleright$  conservation equation for in situ temperature T

$$\rho c_{p} \frac{DT}{Dt} = \alpha T \frac{Dp}{Dt} + \frac{\partial H}{\partial S} \nabla \cdot \boldsymbol{J}_{S} - \nabla \cdot \boldsymbol{J}_{H} + \rho \epsilon$$

with enthalpy H, specific heat  $c_p = \partial H/\partial T$ , thermal expansion coefficient  $\alpha = -1/\rho \, \partial \rho/\partial T$ , kinetic energy dissipation  $\rho \epsilon = \Sigma_{ij}^2$  and molecular diffusive enthalpy flux  $J_H$ 

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▶ assume adiabatic conditions, i.e.  $J_S = 0$ ,  $J_H = 0$  and  $\epsilon = 0$ 

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with adiabatic lapse rate  $\Gamma = \alpha T / (\rho c_p)$ 

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in situ temperature is not "conserved"

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conservation equation for in situ temperature T

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- in situ temperature is not "conserved"
- changes in temperature and pressure are related by  $dT = \Gamma dp$
- adiabatic lapse rate can also be defined by  $\Gamma = (\partial T / \partial p)_{ad}$
- ▶ typical value is  $\Gamma \approx 10^{-8} \, {\rm K/Pa} = 10^{-4} \, {\rm K/dbar} \sim 0.1 \, {\rm K/km}$

$$\rho \frac{D\Theta}{Dt} = \left(\frac{\theta}{T} \frac{\partial H}{\partial S} - \frac{\partial H^0}{\partial S}\right) \nabla \cdot \frac{J_S}{c_\rho^\star} + \frac{\theta}{T} \left(-\nabla \cdot \frac{J_H}{c_\rho^\star} + \rho \frac{\epsilon}{c_\rho^\star}\right)$$

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- now assume  $\theta/T \approx 1$  with relative error of  $10^{-3}$
- neglect effect of salt fluxes compared to heat flux term  $J_H$

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- now assume heta/T pprox 1 with relative error of  $10^{-3}$
- neglect effect of salt fluxes compared to heat flux term  $J_H$
- neglect effect of dissipation compared to heat flux term
- get temperature equation containing the divergence of  $J_H$

$$ho rac{D\Theta}{Dt} = - oldsymbol{
abla} \cdot oldsymbol{J}_{\Theta} + ext{very small source term}$$

with  $oldsymbol{J}_{\Theta}=oldsymbol{J}_{H}/c_{p}^{\star}$ 

#### Recapitulation

Euler/Lagrange framework General conservation equation Continuity or mass conservation equation Salinity and salt conservation Momentum or Navier Stokes equation Heat and temperature equation Rotating earth

### Approximations and simplifications

Boussinesq approximation Hydrostatic approximation

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 $\blacktriangleright$  a new coordinate system rotates with  $\Omega$ 

$$rac{Doldsymbol{X}}{Dt} = oldsymbol{u} = oldsymbol{u}^{rot} + oldsymbol{\Omega} imes oldsymbol{X}$$

velocity within the rotating frame is  $u^{rot}$ 



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 $\blacktriangleright$  a new coordinate system rotates with  $\Omega$ 

$$\frac{D\boldsymbol{X}}{Dt} = \boldsymbol{u} = \boldsymbol{u}^{rot} + \boldsymbol{\Omega} \times \boldsymbol{X} \quad \rightarrow \quad \frac{D\boldsymbol{X}}{Dt} = \left(\frac{D}{Dt}\right)^{rot} \boldsymbol{X} + \boldsymbol{\Omega} \times \boldsymbol{X}$$

velocity within the rotating frame is  $\boldsymbol{u}^{rot} = (D/Dt)^{rot} \boldsymbol{X}$ temporal change within the rotating frame is  $(D/Dt)^{rot}$ 

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velocity within the rotating frame is  $\boldsymbol{u}^{rot} = (D/Dt)^{rot} \boldsymbol{X}$ temporal change within the rotating frame is  $(D/Dt)^{rot}$ 

• for the acceleration,  $D\boldsymbol{u}/Dt = D^2\boldsymbol{X}/Dt^2$  we find

$$rac{Doldsymbol{u}}{Dt} = rac{Doldsymbol{u}^{rot}}{Dt} + oldsymbol{\Omega} imes rac{Doldsymbol{X}}{Dt}$$

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$$\frac{D\boldsymbol{u}}{Dt} = \frac{D\boldsymbol{u}^{rot}}{Dt} + \boldsymbol{\Omega} \times \frac{D\boldsymbol{X}}{Dt} = \left(\frac{D}{Dt}\right)^{rot} \boldsymbol{u}^{rot} + \boldsymbol{\Omega} \times \boldsymbol{u}^{rot} + \boldsymbol{\Omega} \times \left(\boldsymbol{u}^{rot} + \boldsymbol{\Omega} \times \boldsymbol{X}\right)$$

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$$\frac{D\boldsymbol{X}}{Dt} = \boldsymbol{u} = \boldsymbol{u}^{rot} + \boldsymbol{\Omega} \times \boldsymbol{X} \quad \rightarrow \quad \frac{D\boldsymbol{X}}{Dt} = \left(\frac{D}{Dt}\right)^{rot} \boldsymbol{X} + \boldsymbol{\Omega} \times \boldsymbol{X}$$

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$$\begin{aligned} \frac{D\boldsymbol{u}}{Dt} &= \frac{D\boldsymbol{u}^{rot}}{Dt} + \boldsymbol{\Omega} \times \frac{D\boldsymbol{X}}{Dt} \\ &= \left(\frac{D}{Dt}\right)^{rot} \boldsymbol{u}^{rot} + \boldsymbol{\Omega} \times \boldsymbol{u}^{rot} + \boldsymbol{\Omega} \times \left(\boldsymbol{u}^{rot} + \boldsymbol{\Omega} \times \boldsymbol{X}\right) \\ &= \left(\frac{D}{Dt}\right)^{rot} \boldsymbol{u}^{rot} + 2\boldsymbol{\Omega} \times \boldsymbol{u}^{rot} + \boldsymbol{\Omega} \times (\boldsymbol{\Omega} \times \boldsymbol{X}) \end{aligned}$$

- $D\boldsymbol{u}/Dt$  is the acceleration of the fluid element in the absolute frame  $(D/Dt)^{rot}\boldsymbol{u}^{rot}$  is the acceleration measured by a co-rotating observer
- ▶ two additional (apparent) forces: Coriolis and centrifugal force

Recapitulation

Rotating earth

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momentum equation in rotating frame

$$\rho \frac{D\boldsymbol{u}}{Dt} = \rho \left(\frac{D}{Dt}\right)^{rot} \boldsymbol{u}^{rot} + 2\rho \boldsymbol{\Omega} \times \boldsymbol{u}^{rot} + \rho \boldsymbol{\Omega} \times (\boldsymbol{\Omega} \times \boldsymbol{X})$$
$$= -\boldsymbol{\nabla} \rho + \boldsymbol{\nabla} \cdot \boldsymbol{\Sigma} + \boldsymbol{f}^{v}$$

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momentum equation in rotating frame

$$\rho \frac{D\boldsymbol{u}}{Dt} = \rho \left(\frac{D}{Dt}\right)^{rot} \boldsymbol{u}^{rot} + 2\rho \boldsymbol{\Omega} \times \boldsymbol{u}^{rot} + \rho \boldsymbol{\Omega} \times (\boldsymbol{\Omega} \times \boldsymbol{X})$$
$$= -\nabla \boldsymbol{p} + \boldsymbol{\nabla} \cdot \boldsymbol{\Sigma} + \boldsymbol{f}^{\vee}$$

or, dropping the index <sup>rot</sup> from now on

$$\rho \frac{D \boldsymbol{u}}{D t} = -\boldsymbol{\nabla} p - 2\rho \boldsymbol{\Omega} \times \boldsymbol{u} + \boldsymbol{\nabla} \cdot \boldsymbol{\Sigma} + \boldsymbol{f}^{\boldsymbol{\nu}} - \rho \boldsymbol{\Omega} \times (\boldsymbol{\Omega} \times \boldsymbol{X})$$

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momentum equation in rotating frame

$$\rho \frac{D\boldsymbol{u}}{Dt} = \rho \left(\frac{D}{Dt}\right)^{rot} \boldsymbol{u}^{rot} + 2\rho \boldsymbol{\Omega} \times \boldsymbol{u}^{rot} + \rho \boldsymbol{\Omega} \times (\boldsymbol{\Omega} \times \boldsymbol{X})$$
$$= -\nabla \boldsymbol{p} + \boldsymbol{\nabla} \cdot \boldsymbol{\Sigma} + \boldsymbol{f}^{\vee}$$

or, dropping the index rot from now on

$$\rho \frac{D \boldsymbol{u}}{D t} = -\boldsymbol{\nabla} \boldsymbol{p} - 2\rho \boldsymbol{\Omega} \times \boldsymbol{u} + \boldsymbol{\nabla} \cdot \boldsymbol{\Sigma} + \boldsymbol{f}^{\boldsymbol{\nu}} - \rho \boldsymbol{\Omega} \times (\boldsymbol{\Omega} \times \boldsymbol{X})$$

• with the Coriolis force  $-2
ho {f \Omega} imes {m u}$ 

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- with the Coriolis force  $-2
  ho \mathbf{\Omega} imes \mathbf{u}$
- and the centrifugal force  $-\rho \mathbf{\Omega} imes (\mathbf{\Omega} imes \mathbf{X})$

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momentum equation in rotating frame

$$\rho \frac{D\boldsymbol{u}}{Dt} = \rho \left(\frac{D}{Dt}\right)^{rot} \boldsymbol{u}^{rot} + 2\rho \boldsymbol{\Omega} \times \boldsymbol{u}^{rot} + \rho \boldsymbol{\Omega} \times (\boldsymbol{\Omega} \times \boldsymbol{X})$$
$$= -\boldsymbol{\nabla} \boldsymbol{p} + \boldsymbol{\nabla} \cdot \boldsymbol{\Sigma} + \boldsymbol{f}^{\mathsf{v}}$$

or, dropping the index <sup>rot</sup> from now on

$$\rho \frac{D\boldsymbol{u}}{D\boldsymbol{t}} = -\boldsymbol{\nabla}\boldsymbol{p} - 2\rho\boldsymbol{\Omega} \times \boldsymbol{u} + \boldsymbol{\nabla} \cdot \boldsymbol{\Sigma} + \boldsymbol{f}^{\boldsymbol{v}} - \rho\boldsymbol{\Omega} \times (\boldsymbol{\Omega} \times \boldsymbol{X})$$

- with the Coriolis force  $-2\rho \mathbf{\Omega} \times \boldsymbol{u}$
- and the centrifugal force  $ho \mathbf{\Omega} imes (\mathbf{\Omega} imes \mathbf{X})$
- The combined force in the equation of motion is given by

$$-
ho \mathbf{\Omega} imes (\mathbf{\Omega} imes \mathbf{X}) - 
ho \mathbf{\nabla} \Phi_E = -
ho \mathbf{\nabla} \Phi$$

Rotating earth

### Summary conservation laws

momentum equation

$$\rho \frac{D \boldsymbol{u}}{D t} = -\boldsymbol{\nabla} \boldsymbol{\rho} - 2\rho \boldsymbol{\Omega} \times \boldsymbol{u} + \boldsymbol{\nabla} \cdot \boldsymbol{\Sigma} - \rho \boldsymbol{\nabla} (\boldsymbol{\Phi} + \boldsymbol{\Phi}_{tide})$$

with geopotential ( $\Phi = gz$ ) and tidal potential  $\Phi_{\textit{tide}}(\pmb{x},t)$ 

continuity equation

$$rac{D
ho}{Dt} = -
ho oldsymbol{
abla} \cdot oldsymbol{u} \ , \ \ 
ho rac{Doldsymbol{v}}{Dt} = oldsymbol{
abla} \cdot oldsymbol{u}$$

salt conservation equation

$$\rho \frac{DS}{Dt} = -\boldsymbol{\nabla} \cdot \boldsymbol{J}_S$$

conservative temperature equation

$$\rho \frac{D\Theta}{Dt} = -\nabla \cdot \boldsymbol{J}_{\Theta} + \text{very small source term}$$

equation of state with conservative temperature as state variable

$$\rho = \rho(S, \Theta, p)$$

### Recapitulation

Euler/Lagrange framework General conservation equation Continuity or mass conservation equation Salinity and salt conservation Momentum or Navier Stokes equation Heat and temperature equation Rotating earth

# Approximations and simplifications

## Boussinesq approximation

Hydrostatic approximation

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$$rac{\partial 
ho}{\partial t} = - oldsymbol{
abla} \cdot (
ho oldsymbol{u})$$

$$rac{\partial 
ho}{\partial t} = - \boldsymbol{\nabla} \cdot (
ho \boldsymbol{u})$$

introduce scaled variables with primes

$$\rho = \rho_0 \rho$$
 ,  $\boldsymbol{u} = U \boldsymbol{u}'$  ,  $\boldsymbol{x} = L \boldsymbol{x}'$  ,  $t = T t'$ 

with the dimensionless functions  $\rho'$ ,  $\boldsymbol{u}'$ , etc of O(1)with constants  $\rho_0$ , U taking dimensions and magnitudes and with  $\partial/\partial t = (1/T)\partial/\partial t'$ , and  $\partial/\partial x = (1/L)\partial/\partial x'$ , etc

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ho}{\partial t} = - \boldsymbol{\nabla} \cdot (
ho \boldsymbol{u})$$

introduce scaled variables with primes

$$\rho = \rho_0 \rho$$
 ,  $\boldsymbol{u} = U \boldsymbol{u}'$  ,  $\boldsymbol{x} = L \boldsymbol{x}'$  ,  $t = T t'$ 

with the dimensionless functions  $\rho'$ , u', etc of O(1)with constants  $\rho_0$ , U taking dimensions and magnitudes and with  $\partial/\partial t = (1/T)\partial/\partial t'$ , and  $\partial/\partial x = (1/L)\partial/\partial x'$ , etc  $\blacktriangleright$  this yields

$$\frac{\rho_0}{T} \frac{\partial \rho'}{\partial t'} = -\frac{\rho_0 U}{L} \nabla' \cdot (\rho' \mathbf{u}')$$
$$\frac{\partial \rho'}{\partial t'} = -\frac{UT}{L} \nabla' \cdot (\rho' \mathbf{u}')$$

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ho}{\partial t} = - \boldsymbol{\nabla} \cdot (
ho \boldsymbol{u})$$

introduce scaled variables with primes

$$\rho=\rho_0\rho~,~\boldsymbol{u}=\boldsymbol{U}\boldsymbol{u}'~,~\boldsymbol{x}=\boldsymbol{L}\boldsymbol{x}'~,~\boldsymbol{t}=\boldsymbol{T}\boldsymbol{t}'$$

with the dimensionless functions  $\rho'$ , u', etc of O(1)with constants  $\rho_0$ , U taking dimensions and magnitudes and with  $\partial/\partial t = (1/T)\partial/\partial t'$ , and  $\partial/\partial x = (1/L)\partial/\partial x'$ , etc  $\blacktriangleright$  this yields

$$\frac{\rho_0}{T} \frac{\partial \rho'}{\partial t'} = -\frac{\rho_0 U}{L} \nabla' \cdot (\rho' \boldsymbol{u}')$$
$$\frac{\partial \rho'}{\partial t'} = -\frac{UT}{L} \nabla' \cdot (\rho' \boldsymbol{u}')$$

now forget all primes

$$\frac{\partial \rho}{\partial t} = -\frac{UT}{L} \boldsymbol{\nabla} \cdot (\rho \boldsymbol{u})$$

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equation of state for seawater

$$\rho = \rho(S, T, p)$$

function of salinity S, temperature T and pressure p

- no analytical (exact) expressions for the function  $\rho(S, T, p)$
- ► empirical expressions with relative accuracy of (3 5) × 10<sup>-6</sup> → TEOS: http://www.teos-10.org/



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$$\frac{\partial \rho}{\partial t} = -\boldsymbol{\nabla} \cdot (\rho \boldsymbol{u})$$

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ho}{\partial t} = - oldsymbol{
abla} \cdot (
ho oldsymbol{u})$$

▶ better scaling than  $\rho = \rho_0 \rho'$  is given by  $\rho = \rho_0 + \rho \rho'$ with a large mean value  $\rho_0 = 1000 \text{ kg/m}^3$ plus small variations with magnitude  $\rho = 10 \text{ kg/m}^3$ 

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$$rac{\partial 
ho}{\partial t} = - oldsymbol{
abla} \cdot (
ho oldsymbol{u})$$

- ▶ better scaling than  $\rho = \rho_0 \rho'$  is given by  $\rho = \rho_0 + \rho \rho'$ with a large mean value  $\rho_0 = 1000 \, \mathrm{kg/m^3}$ plus small variations with magnitude  $\rho = 10 \, \mathrm{kg/m^3}$
- this yields in the continuity equation

$$\frac{1}{T}\frac{\partial}{\partial t'}(\rho_0+\varrho\rho') = -\frac{U}{L}\boldsymbol{\nabla}'\cdot((\rho_0+\varrho\rho')\boldsymbol{u}')$$

$$rac{\partial 
ho}{\partial t} = - \boldsymbol{\nabla} \cdot (
ho \boldsymbol{u})$$

- ▶ better scaling than  $\rho = \rho_0 \rho'$  is given by  $\rho = \rho_0 + \rho \rho'$ with a large mean value  $\rho_0 = 1000 \, \mathrm{kg/m^3}$ plus small variations with magnitude  $\rho = 10 \, \mathrm{kg/m^3}$
- this yields in the continuity equation

$$\frac{1}{T}\frac{\partial}{\partial t'}(\rho_0 + \varrho \rho') = -\frac{U}{L}\boldsymbol{\nabla}' \cdot ((\rho_0 + \varrho \rho')\boldsymbol{u}')$$
$$\frac{\partial \rho'}{\partial t'} = -\frac{\rho_0}{\varrho}\frac{UT}{L}\boldsymbol{\nabla}' \cdot \boldsymbol{u}' - \frac{UT}{L}\boldsymbol{\nabla}' \cdot (\rho'\boldsymbol{u}')$$

$$rac{\partial 
ho}{\partial t} = - \boldsymbol{\nabla} \cdot (
ho \boldsymbol{u})$$

- ▶ better scaling than  $\rho = \rho_0 \rho'$  is given by  $\rho = \rho_0 + \rho \rho'$ with a large mean value  $\rho_0 = 1000 \, \mathrm{kg/m^3}$ plus small variations with magnitude  $\rho = 10 \, \mathrm{kg/m^3}$
- this yields in the continuity equation

$$\frac{1}{T}\frac{\partial}{\partial t'}(\rho_0 + \varrho \rho') = -\frac{U}{L}\boldsymbol{\nabla}' \cdot ((\rho_0 + \varrho \rho')\boldsymbol{u}')$$
$$\frac{\partial \rho'}{\partial t'} = -\frac{\rho_0}{\varrho}\frac{UT}{L}\boldsymbol{\nabla}' \cdot \boldsymbol{u}' - \frac{UT}{L}\boldsymbol{\nabla}' \cdot (\rho'\boldsymbol{u}')$$

▶ since  $\rho_0/\varrho \gg 1$  and rest of O(1) (as long as  $UT/L \ge O(1)$ ) it follows that

mass conservation is replaced by volume conservation

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momentum equation (without friction and tides)

$$\rho \frac{D\boldsymbol{u}}{Dt} = -\boldsymbol{\nabla}\boldsymbol{p} - 2\rho \boldsymbol{\Omega} \times \boldsymbol{u} - \rho \boldsymbol{\nabla} \boldsymbol{\Phi}$$



momentum equation (without friction and tides)

$$\rho \frac{D\boldsymbol{u}}{Dt} = -\boldsymbol{\nabla}\boldsymbol{p} - 2\rho \boldsymbol{\Omega} \times \boldsymbol{u} - \rho \boldsymbol{\nabla} \boldsymbol{\Phi}$$

• using  $\rho = \rho_0 + \varrho \rho'$  yields

$$(\rho_0 + \varrho \rho') \frac{D \boldsymbol{u}}{Dt} = -\boldsymbol{\nabla} \boldsymbol{p} - 2(\rho_0 + \varrho \rho') \boldsymbol{\Omega} \times \boldsymbol{u} - (\rho_0 + \varrho \rho') \boldsymbol{\nabla} \phi$$

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momentum equation (without friction and tides)

$$\rho \frac{D\boldsymbol{u}}{Dt} = -\boldsymbol{\nabla}\boldsymbol{p} - 2\rho \boldsymbol{\Omega} \times \boldsymbol{u} - \rho \boldsymbol{\nabla} \boldsymbol{\Phi}$$

• using  $\rho = \rho_0 + \varrho \rho'$  yields

$$(\rho_0 + \varrho \rho') \frac{D \boldsymbol{u}}{D t} = -\boldsymbol{\nabla} \boldsymbol{p} - 2(\rho_0 + \varrho \rho') \boldsymbol{\Omega} \times \boldsymbol{u} - (\rho_0 + \varrho \rho') \boldsymbol{\nabla} \phi$$

• consider 3. component for  $\boldsymbol{u} = 0$  and  $\phi = gz$ 

$$rac{\partial m{
ho}}{\partial z} = -(
ho_0 + arrho 
ho') m{g} pprox - 
ho_0 m{g}$$

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▶ motivates to set  $p \equiv p_0(z) + p'$  with  $p_0 \gg p'$  and to set  $\frac{\partial p_0}{\partial z} \equiv -\rho_0 g$ 

hydrostatic balance of  $p_0$  with constant density  $\rho_0$ 

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consider a column of the ocean





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consider a column of the ocean



pressure force at bottom  $F_B = p\delta A$   $\delta_Z$  pressure force at top  $F_T = -(p + \delta p)\delta A$ 

(positive upward)

consider a column of the ocean



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consider a column of the ocean



• mass of cylinder is  $M = \rho \delta A \delta z$  and gravity force is  $F_g = -gM$ 

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consider a column of the ocean



- mass of cylinder is  $M = \rho \delta A \delta z$  and gravity force is  $F_g = -gM$
- if no other forces act and column does not accelerate

$$F_B + F_T + F_g = 0$$

consider a column of the ocean



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- mass of cylinder is  $M = \rho \delta A \delta z$  and gravity force is  $F_g = -gM$
- ► if no other forces act and column does not accelerate  $F_B + F_T + F_g = 0 \rightarrow p\delta A - (p + \frac{\partial p}{\partial z}\delta z)\delta A - g\rho\delta A\delta z = 0$

consider a column of the ocean



- mass of cylinder is  $M = \rho \delta A \delta z$  and gravity force is  $F_g = -gM$
- if no other forces act and column does not accelerate

$$F_B + F_T + F_g = 0 \rightarrow p\delta A - (p + \frac{\partial p}{\partial z}\delta z)\delta A - g\rho\delta A\delta z = 0$$

or

$$-rac{\partial p}{\partial z} - g
ho = 0 \ 
ightarrow$$
 hydrostatic balance

#### momentum equation becomes

$$(\rho_0 + \varrho \rho') \frac{D \boldsymbol{u}}{Dt} = -\boldsymbol{\nabla}(\rho_0(z) + \rho') - 2(\rho_0 + \varrho \rho') \boldsymbol{\Omega} \times \boldsymbol{u} - (\rho_0 + \varrho \rho') \boldsymbol{\nabla} \phi$$

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since by construction

$$-rac{\partial p_0}{\partial z} - g 
ho_0 = 0$$
 or  $- \nabla p_0(z) - 
ho_0 \nabla \phi = 0$ 

background gravity and vertical pressure gradient completely drop

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momentum equation becomes

$$(\rho_0 + \varrho \rho') \frac{D \boldsymbol{u}}{Dt} = -\boldsymbol{\nabla}(\boldsymbol{p}_0(\boldsymbol{z}) + \boldsymbol{p}') - 2(\rho_0 + \varrho \rho') \boldsymbol{\Omega} \times \boldsymbol{u} - (\rho_0 + \varrho \rho') \boldsymbol{\nabla} \phi$$

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▶ since  $\rho_0 \gg \varrho$  momentum equation further simplifies to

$$ho_0 rac{D oldsymbol{u}}{D t} ~pprox - oldsymbol{
abla} oldsymbol{p}' - 2
ho_0 oldsymbol{\Omega} imes oldsymbol{u} - arrho 
ho' oldsymbol{
abla} \phi$$

finally set  ${\it p}' \rightarrow {\it p}$  and  $\varrho \rho' \rightarrow \rho$ 

but remember that pressure p and density  $\rho$  are now perturbations

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momentum equation becomes

$$(\rho_0 + \varrho \rho') \frac{D \boldsymbol{u}}{Dt} = -\boldsymbol{\nabla}(\boldsymbol{p}_0(\boldsymbol{z}) + \boldsymbol{p}') - 2(\rho_0 + \varrho \rho') \boldsymbol{\Omega} \times \boldsymbol{u} - (\rho_0 + \varrho \rho') \boldsymbol{\nabla} \phi$$

since by construction

$$-rac{\partial p_0}{\partial z} - g 
ho_0 = 0$$
 or  $- \nabla p_0(z) - 
ho_0 \nabla \phi = 0$ 

background gravity and vertical pressure gradient completely drop

▶ since  $\rho_0 \gg \varrho$  momentum equation further simplifies to

$$\rho_0 rac{D \boldsymbol{u}}{D t} \approx - \boldsymbol{\nabla} \boldsymbol{p}' - 2 \rho_0 \boldsymbol{\Omega} \times \boldsymbol{u} - \varrho \rho' \boldsymbol{\nabla} \phi$$

finally set  ${\it p}' \rightarrow {\it p}$  and  $\varrho \rho' \rightarrow \rho$ 

but remember that pressure p and density  $\rho$  are now perturbations

• salinity equation with  $\rho = \rho_0 + \rho \rho'$  becomes

$$(\rho_0 + \varrho \rho') \frac{DS}{Dt} = - \boldsymbol{\nabla} \cdot \boldsymbol{J}_S \quad \rightarrow \quad \rho_0 \frac{DS}{Dt} \approx - \boldsymbol{\nabla} \cdot \boldsymbol{J}_S$$

and similar for temperature

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Boussinesq approximation

### Summary exact conservation laws

momentum equation

$$\rho \frac{D \boldsymbol{u}}{D t} = -\boldsymbol{\nabla} \boldsymbol{\rho} - 2\rho \boldsymbol{\Omega} \times \boldsymbol{u} + \boldsymbol{\nabla} \cdot \boldsymbol{\Sigma} - \rho \boldsymbol{\nabla} (\boldsymbol{\Phi} + \boldsymbol{\Phi}_{tide})$$

with geopotential ( $\Phi = gz$ ) and tidal potential  $\Phi_{\textit{tide}}(\pmb{x},t)$ 

continuity equation

$$\frac{D\rho}{Dt} = -\rho \boldsymbol{\nabla} \cdot \boldsymbol{u} \ , \ \rho \frac{Dv}{Dt} = \boldsymbol{\nabla} \cdot \boldsymbol{u}$$

salt conservation equation

$$\rho \frac{DS}{Dt} = -\boldsymbol{\nabla} \cdot \boldsymbol{J}_S$$

conservative temperature equation

$$\rho \frac{D\Theta}{Dt} = -\nabla \cdot \boldsymbol{J}_{\Theta} + \text{very small source term}$$

equation of state with conservative temperature as state variable

$$\rho = \rho(S, \Theta, p)$$

Conservation laws in Boussinesq approximation

momentum equation

$$\rho_0 \frac{D \boldsymbol{u}}{D t} = -\boldsymbol{\nabla} \boldsymbol{p} - 2\rho_0 \boldsymbol{\Omega} \times \boldsymbol{u} + \boldsymbol{\nabla} \cdot \boldsymbol{\Sigma} - \rho \boldsymbol{\nabla} (\boldsymbol{\Phi} + \boldsymbol{\Phi}_{tide})$$

with geopotential ( $\Phi = gz$ ) and tidal potential  $\Phi_{tide}(\mathbf{x},t)$ 

continuity equation

$$0 = \boldsymbol{\nabla} \cdot \boldsymbol{u}$$

salt conservation equation

$$\rho_0 \frac{DS}{Dt} = -\boldsymbol{\nabla} \cdot \boldsymbol{J}_S$$

conservative temperature equation

$$\rho_0 \frac{D\Theta}{Dt} = -\nabla \cdot \boldsymbol{J}_{\Theta} + \text{very small source term}$$

equation of state with conservative temperature as state variable

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# Recapitulation

Euler/Lagrange framework General conservation equation Continuity or mass conservation equation Salinity and salt conservation Momentum or Navier Stokes equation Heat and temperature equation Rotating earth

Approximations and simplifications

Boussinesq approximation Hydrostatic approximation

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$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0 \quad \rightarrow \quad \frac{U}{L} \left( \frac{\partial u'}{\partial x'} + \frac{\partial v'}{\partial y'} \right) + \frac{W}{H} \frac{\partial w'}{\partial z'} = 0$$

with lateral scale L and vertical scale Hand lateral velocity scale U and vertical velocity scale W

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$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0 \quad \rightarrow \quad \frac{U}{L} \left( \frac{\partial u'}{\partial x'} + \frac{\partial v'}{\partial y'} \right) + \frac{W}{H} \frac{\partial w'}{\partial z'} = 0$$

with lateral scale L and vertical scale Hand lateral velocity scale U and vertical velocity scale W

 For W/H ≫ U/L it follows that ∂w/∂z = 0 such that w = 0 considering bottom or top boundaries
 → scaling becomes inconsistent

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$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0 \quad \rightarrow \quad \frac{U}{L} \left( \frac{\partial u'}{\partial x'} + \frac{\partial v'}{\partial y'} \right) + \frac{W}{H} \frac{\partial w'}{\partial z'} = 0$$

with lateral scale L and vertical scale Hand lateral velocity scale U and vertical velocity scale W

 For W/H ≫ U/L it follows that ∂w/∂z = 0 such that w = 0 considering bottom or top boundaries
 → scaling becomes inconsistent

▶ only cases  $W/H \sim U/L$  or  $W/H \ll U/L$  are possible

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$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0 \quad \rightarrow \quad \frac{U}{L} \left( \frac{\partial u'}{\partial x'} + \frac{\partial v'}{\partial y'} \right) + \frac{W}{H} \frac{\partial w'}{\partial z'} = 0$$

with lateral scale L and vertical scale Hand lateral velocity scale U and vertical velocity scale W

- only cases  $W/H \sim U/L$  or  $W/H \ll U/L$  are possible
- ▶ now define aspect ratio  $\delta = H/L$  ("deepness" of the flow) with

$$W = UH/L = \delta U$$

which means that for  $\delta \sim 1 \ \rightarrow \ W \sim U$  and for  $\delta \ll 1 \ \rightarrow \ W \ll U$ 

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0 \quad \rightarrow \quad \frac{U}{L} \left( \frac{\partial u'}{\partial x'} + \frac{\partial v'}{\partial y'} \right) + \frac{W}{H} \frac{\partial w'}{\partial z'} = 0$$

with lateral scale L and vertical scale Hand lateral velocity scale U and vertical velocity scale W

- only cases  $W/H \sim U/L$  or  $W/H \ll U/L$  are possible
- ▶ now define aspect ratio  $\delta = H/L$  ("deepness" of the flow) with

$$W = UH/L = \delta U$$

which means that for  $\delta \sim 1 \ \rightarrow \ W \sim U$  and for  $\delta \ll 1 \ \rightarrow \ W \ll U$ 

▶ since  $\delta \ll 1$  for large-scale flow in the ocean  $W \ll U$ i.e. shallow water yields small (but still important!) w

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momentum equation in rotating frame (no friction, no tides)

$$\rho_0 \frac{D\boldsymbol{u}}{Dt} = -\boldsymbol{\nabla}\boldsymbol{\rho} - 2\rho_0 \boldsymbol{\Omega} \times \boldsymbol{u} + \rho \boldsymbol{\nabla}\phi$$



momentum equation in rotating frame (no friction, no tides)

$$\rho_0 \frac{D \boldsymbol{u}}{D t} = -\boldsymbol{\nabla} \boldsymbol{p} - 2\rho_0 \boldsymbol{\Omega} \times \boldsymbol{u} + \rho \boldsymbol{\nabla} \phi$$

• with  $\mathbf{\Omega} = (\mathbf{0}, \Omega \cos \varphi, \Omega \sin \varphi)$ 

$$\boldsymbol{\Omega} \times \boldsymbol{u} = \boldsymbol{\Omega} \begin{pmatrix} \boldsymbol{0} \\ \cos \varphi \\ \sin \varphi \end{pmatrix} \times \begin{pmatrix} \boldsymbol{u} \\ \boldsymbol{v} \\ \boldsymbol{w} \end{pmatrix} = \boldsymbol{\Omega} \begin{pmatrix} w \cos \varphi - v \sin \varphi \\ u \sin \varphi \\ -u \cos \varphi \end{pmatrix}$$



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- ▶ aspect ratio  $\delta = H/L \ll 1$  ,  $W = \delta U$
- momentum equation in rotating frame (no friction, no tides)

$$\rho_0 \frac{D\boldsymbol{u}}{Dt} = -\boldsymbol{\nabla} \boldsymbol{p} - 2\rho_0 \boldsymbol{\Omega} \times \boldsymbol{u} + \rho \boldsymbol{\nabla} \phi$$

- aspect ratio  $\delta = H/L \ll 1$  ,  $W = \delta U$
- momentum equation in rotating frame (no friction, no tides)

$$\rho_0 \frac{D\boldsymbol{u}}{Dt} = -\boldsymbol{\nabla}\boldsymbol{p} - 2\rho_0 \boldsymbol{\Omega} \times \boldsymbol{u} + \rho \boldsymbol{\nabla}\phi$$

consider first momentum equation

$$\frac{\partial u}{\partial t} + \boldsymbol{u} \cdot \boldsymbol{\nabla} u = -\frac{1}{\rho_0} \frac{\partial \boldsymbol{p}}{\partial x} - 2\Omega(\boldsymbol{w} \cos \varphi - \boldsymbol{v} \sin \varphi)$$

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- aspect ratio  $\delta = H/L \ll 1$  ,  $W = \delta U$
- momentum equation in rotating frame (no friction, no tides)

$$\rho_0 \frac{D\boldsymbol{u}}{Dt} = -\boldsymbol{\nabla}\boldsymbol{p} - 2\rho_0 \boldsymbol{\Omega} \times \boldsymbol{u} + \rho \boldsymbol{\nabla}\phi$$

consider first momentum equation

$$\frac{\partial u}{\partial t} + \boldsymbol{u} \cdot \boldsymbol{\nabla} \boldsymbol{u} = -\frac{1}{\rho_0} \frac{\partial \boldsymbol{p}}{\partial \boldsymbol{x}} - 2\Omega(\boldsymbol{w} \cos \varphi - \boldsymbol{v} \sin \varphi)$$

scaling of each term yields

$${U\over T}$$
 ,  $\left({U^2\over L}\,,\,{WU\over H}
ight)$  ~  ${P\over 
ho_0 L}$  ,  $\Omega W$  ,  $\Omega U$ 

divide by  $\Omega U$  to get magnitudes relative to (vertical) Coriolis force

$$rac{1}{T\Omega}$$
 ,  $rac{U}{L\Omega}$  ~  $rac{P}{
ho_0 L\Omega U}$  ,  $\delta \ll 1$  ,  $1$ 

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- aspect ratio  $\delta = H/L \ll 1$  ,  $W = \delta U$
- consider first momentum equation

$$\frac{\partial u}{\partial t} + \boldsymbol{u} \cdot \boldsymbol{\nabla} \boldsymbol{u} = -\frac{1}{\rho_0} \frac{\partial \boldsymbol{p}}{\partial x} - 2\Omega(\boldsymbol{w} \cos \varphi - \boldsymbol{v} \sin \varphi)$$

scaling yields

$$rac{1}{T\Omega}$$
 ,  $rac{U}{L\Omega}$  ~  $rac{P}{
ho_0 L\Omega U}$  ,  $\delta \ll 1$  ,  $1$ 

consider first momentum equation

$$\frac{\partial u}{\partial t} + \boldsymbol{u} \cdot \boldsymbol{\nabla} u = -\frac{1}{\rho_0} \frac{\partial \boldsymbol{p}}{\partial x} - 2\Omega(\boldsymbol{w} \cos \varphi - \boldsymbol{v} \sin \varphi)$$

scaling yields

$$rac{1}{T\Omega}$$
 ,  $rac{U}{L\Omega}$  ~  $rac{P}{
ho_0 L\Omega U}$  ,  $\delta \ll 1$  ,  $1$ 

► set T = L/U and define Rossby number  $Ro = U/(L\Omega)$ 

$$Ro$$
 ,  $Ro$  ~  $rac{P}{
ho_0 L\Omega U}$  ,  $\delta \ll 1$  ,  $1$ 

► Ro compares momentum advection with Coriolis force for large-scale flow in the ocean Ro ≤ 1

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consider first momentum equation

$$\frac{\partial u}{\partial t} + \boldsymbol{u} \cdot \boldsymbol{\nabla} u = -\frac{1}{\rho_0} \frac{\partial \boldsymbol{p}}{\partial x} - 2\Omega(\boldsymbol{w} \cos \varphi - \boldsymbol{v} \sin \varphi)$$

scaling yields

$$rac{1}{T\Omega}$$
 ,  $rac{U}{L\Omega}$  ~  $rac{P}{
ho_0 L\Omega U}$  ,  $\delta \ll 1$  ,  $1$ 

► set T = L/U and define Rossby number  $Ro = U/(L\Omega)$ 

Ro , Ro 
$$\sim \frac{P}{\rho_0 L \Omega U}$$
 ,  $\delta \ll 1$  ,  $1$ 

- ► Ro compares momentum advection with Coriolis force for large-scale flow in the ocean Ro ≤ 1
- assume dominant geostrophic balance: P/(ρ<sub>0</sub>LΩU) = 1 but still keep terms of O(Ro) (but not those of O(δ))!

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geostrophy: exact balance between pressure and Coriolis force

![](_page_101_Figure_3.jpeg)

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geostrophy: exact balance between pressure and Coriolis force

![](_page_102_Figure_3.jpeg)

▶ thermal wind: combine with hydrostatic balance  $0 = -\partial p/\partial z - g\rho$ 

$$0 = \frac{g}{\rho_0} \frac{\partial}{\partial x} \rho + 2\Omega \frac{\partial v}{\partial z} \sin \varphi$$
$$0 = \frac{g}{\rho_0} \frac{\partial}{\partial y} \rho - 2\Omega \frac{\partial u}{\partial z} \sin \varphi$$

lateral density gradients are related to vertical shear of u and v  $\rightarrow$  "dynamical method" to determine ocean currents

- ▶ aspect ration  $\delta = H/L \ll 1 \rightarrow W = \delta U$
- momentum equation in rotating frame (no friction, no tides)

$$\rho_0 \frac{D\boldsymbol{u}}{Dt} = -\boldsymbol{\nabla}\boldsymbol{p} - 2\rho_0 \boldsymbol{\Omega} \times \boldsymbol{u} + \rho \boldsymbol{\nabla}\phi$$

consider third momentum equation

$$\frac{\partial w}{\partial t} + \boldsymbol{u} \cdot \boldsymbol{\nabla} w = -\frac{1}{\rho_0} \frac{\partial p}{\partial z} + 2u \cos \phi - \frac{\rho g}{\rho_0}$$

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- ▶ aspect ration  $\delta = H/L \ll 1 \rightarrow W = \delta U$
- momentum equation in rotating frame (no friction, no tides)

$$\rho_0 \frac{D\boldsymbol{u}}{Dt} = -\boldsymbol{\nabla}\boldsymbol{p} - 2\rho_0 \boldsymbol{\Omega} \times \boldsymbol{u} + \rho \boldsymbol{\nabla}\phi$$

consider third momentum equation

$$\frac{\partial w}{\partial t} + \boldsymbol{u} \cdot \boldsymbol{\nabla} w = -\frac{1}{\rho_0} \frac{\partial p}{\partial z} + 2u \cos \phi - \frac{\rho g}{\rho_0}$$

scaling yields

$$\frac{W}{T}$$
 ,  $\left(\frac{UW}{L}$  ,  $\frac{W^2}{H}\right)$  ~  $\frac{P}{\rho_0 H}$  ,  $\Omega U$  ,  $\frac{\varrho g}{\rho_0}$ 

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ho_0 H}$  ,  $\Omega U$  ,  $rac{\varrho g}{
ho_0}$ 

• use  $W = \delta U$  and T = L/U and scaling for  $P = \rho_0 L \Omega U$ 

$${\delta U^2\over L}$$
 ,  ${\delta U^2\over L}$  ~  ${L\Omega U\over H}$  ,  $\Omega U$  ,  ${\varrho g\over 
ho_0}$ 

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scaling yields

$$rac{\delta U^2}{L}$$
 ,  $rac{\delta U^2}{L}$   $\sim$   $rac{L\Omega U}{H}$  ,  $\Omega U$  ,  $rac{arrho g}{
ho_0}$ 

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$$rac{\delta U^2}{L}$$
 ,  $rac{\delta U^2}{L}$  ~  $rac{L\Omega U}{H}$  ,  $\Omega U$  ,  $rac{\varrho g}{
ho_0}$ 

• now multiply with  $\delta$  and divide by  $\Omega U$ 

$$\frac{\delta^2 U^2}{L\Omega U} = \delta^2 R o \ , \ \frac{\delta^2 U^2}{L\Omega U} = \delta^2 R o \ \sim \ 1 \ , \ \delta \ , \ \frac{\delta \varrho g}{\rho_0 \Omega U} \sim 1$$

all magnitudes are now relative to vertical pressure force
- ▶ aspect ration  $\delta = H/L \ll 1 \rightarrow W = \delta U$
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all magnitudes are now relative to vertical pressure force all terms except  $\partial p/\partial z$  and gravity are  $O(\delta)$  or smaller

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- all terms except  $\partial p/\partial z$  and gravity are  $O(\delta)$  or smaller
- ▶ since  $\delta \ll 1$  neglect all terms except  $\partial p / \partial z$  and gravity → hydrostatic approximation

Summary hydrostatic approximation

momentum equation in Boussinesq

$$\rho_0 \frac{D\boldsymbol{u}}{Dt} = -\boldsymbol{\nabla}\boldsymbol{p} - 2\rho_0 \boldsymbol{\Omega} \times \boldsymbol{u} - \rho \boldsymbol{\nabla} \boldsymbol{\Phi}$$

with geopotential ( $\Phi = gz$ ) and tidal potential  $\Phi_{tide}(\textbf{x},t)$ 

becomes

$$\rho_0 \frac{Du}{Dt} = -\frac{\partial p}{\partial x} + 2\rho_0 \Omega v \sin \phi$$
$$\rho_0 \frac{Dv}{Dt} = -\frac{\partial p}{\partial y} - 2\rho_0 \Omega u \sin \phi$$
$$0 = -\frac{\partial p}{\partial z} - g\rho$$

acceleration, advection, etc in 3. momentum equation neglected

- $f = 2\Omega \sin \phi$  is the Coriolis parameter
- $\blacktriangleright$  other equations are unchanged  $\rightarrow$  primitive equations

Planetary geostrophic approximation

momentum equation in Boussinesq

$$\rho_0 \frac{D\boldsymbol{u}}{Dt} = -\boldsymbol{\nabla}\boldsymbol{p} - 2\rho_0 \boldsymbol{\Omega} \times \boldsymbol{u} - \rho \boldsymbol{\nabla} \boldsymbol{\Phi}$$

with geopotential ( $\Phi = gz$ ) and tidal potential  $\Phi_{tide}(\mathbf{x}, t)$ 

• becomes for Rossby number  $Ro \ll 1$ 

$$0 = -\frac{\partial p}{\partial x} + 2\rho_0 \Omega v \sin \phi$$
$$0 = -\frac{\partial p}{\partial y} - 2\rho_0 \Omega u \sin \phi$$
$$0 = -\frac{\partial p}{\partial z} - g\rho$$

acceleration, advection, etc in all momentum equations neglected

• 
$$f = 2\Omega \sin \phi$$
 is the Coriolis parameter

other equations are unchanged